# Publications

Martin Enquist

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#### Theses

[T3] M. Enqvist. Linear Models of Nonlinear Systems. PhD thesis, Linköping University, Linköping, Sweden, 2005

[T2] M. Enqvist. Some results on linear models of nonlinear systems. Licentiate's thesis no. 1046, Department of Electrical Engineering, Linköping University, Linköping, Sweden, 2003

[T1] M. Enqvist. Aspects of high precision estimation of vehicle dynamics. Master's thesis LiTH-ISY-EX-3116, Department of Electrical Engineering, Linköping University, Linköping, Sweden, 2000

### **Book chapters**

[BC1] M. Enqvist. Identification of block-oriented systems using the invariance property. In F. Giri and E.-W. Bai, editors, *Block-oriented Nonlinear System Identification*, pages 147–158. Springer, Berlin Heidelberg, 2010

#### Papers in refereed scientific journals

[J9] J. Linder and M. Enqvist. Identification of systems with unknown inputs using indirect input measurements. *International Journal of Control*, 90(4): 729–745, 2017

[J8] J. Escobar and M. Enqvist. Instrumental variables and LSM in continuoustime parameter estimation. *ESAIM: Control, Optimisation and Calculus of Variations*, 23(2):427–442, 2017

[J7] Y. Jung, J. Fritzin, M. Enqvist, and A. Alvandpour. Least-squares phase predistortion of a +30 dBm class-D outphasing RF PA in 65 nm CMOS. *IEEE Transactions on Circuits and Systems—Part I: Regular Papers*, 60(7):1915–1928, 2013

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[J5] C. Lyzell, T. Glad, M. Enqvist, and L. Ljung. Difference algebra and system identification. Automatica, 47(9):1896–1904, 2011

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[C30] Y. Jung and M. Enqvist. On estimation of approximate inverse models of block-oriented systems. In *Proceedings of the 17th IFAC Symposium on System Identification*, pages 1226–1231, Beijing, China, October 2015

[C29] J. Linder and M. Enqvist. On indirect input measurements. In Proceedings of the 17th IFAC Symposium on System Identification, pages 104–109, Beijing, China, October 2015

[C28] J. Linder, M. Enqvist, T. I. Fossen, T. A. Johansen, and F. Gustafsson. Online estimation of ship's mass and center of mass using inertial measurements. In *Proceedings of the 10th IFAC Conference on Manoeuvring and Control of Marine Craft*, Copenhagen, Denmark, August 2015

[C27] J. Linder, M. Enqvist, T. I. Fossen, T. A. Johansen, and F. Gustafsson. Modeling for IMU-based online estimation of a ship's mass and center of mass. In *Proceedings of the 10th IFAC Conference on Manoeuvring and Control of Marine Craft*, Copenhagen, Denmark, August 2015

[C26] J. Linder, M. Enqvist, and F. Gustafsson. A closed-loop instrumental variable approach to mass and center of mass estimation using IMU data. In *Proceedings of the 53rd IEEE Conference on Decision and Control*, pages 283–289, Los Angeles, California, December 2014

[C25] M. Sadeghi Reineh, M. Enqvist, and F. Gustafsson. IMU-based vehicle load estimation under normal driving conditions. In *Proceedings of the 53rd IEEE Conference on Decision and Control*, pages 3376–3381, Los Angeles, California, December 2014

[C24] J. Linder, M. Enqvist, F. Gustafsson, and J. Sjöberg. Identifiability of physical parameters in systems with limited sensors. In *Proceedings of the 19th IFAC World Congress*, pages 6454–6459, Cape Town, South Africa, August 2014

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[C20] C. Lyzell, M. Andersen, and M. Enqvist. A convex relaxation of a dimension reduction problem using the nuclear norm. In *Proceedings of the 51st IEEE Conference on Decision and Control*, pages 2852–2857, Maui, Hawaii, December 2012

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[C18] C. Lyzell and M. Enqvist. Sliced inverse regression for the identification of dynamical systems. In *Proceedings of the 16th IFAC Symposium on System Identification*, pages 1575–1580, Brussels, Belgium, July 2012

[C17] J. Escobar and M. Enqvist. On the detection of nonlinearities in sampled data. In *Proceedings of the 16th IFAC Symposium on System Identification*, pages 1587–1592, Brussels, Belgium, July 2012

[C16] R. Larsson and M. Enqvist. Sequential aerodynamic model parameter identification. In *Proceedings of the 16th IFAC Symposium on System Identifi*cation, pages 1413–1418, Brussels, Belgium, July 2012

[C15] R. Tóth, C. Lyzell, M. Enqvist, P. S. C. Heuberger, and P. M. J. Van den Hof. Order and structural dependence selection of LPV-ARX models using a nonnegative garrote approach. In *Proceedings of the 48th IEEE Conference on Decision and Control held jointly with 2009 28th Chinese Control Conference*, pages 7406–7411, Shanghai, China, December 2009

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[C12] C. Lyzell, M. Enqvist, and L. Ljung. Handling certain structure information in subspace identification. In *Proceedings of the 15th IFAC Symposium on System Identification*, pages 90–95, Saint-Malo, France, July 2009

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[C10] M. Enqvist. A weighting method for approximate nonlinear system identification. In *Proceedings of the 46th IEEE Conference on Decision and Control*, pages 5104–5109, New Orleans, Louisiana, December 2007

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[C3] M. Enqvist and L. Ljung. LTI approximations of slightly nonlinear systems: Some intriguing examples. In *Proceedings of the 6th IFAC Symposium* on Nonlinear Control Systems, pages 639–644, Stuttgart, Germany, September 2004

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#### Papers at other scientific conferences

[OC5] R. Larsson and M. Enqvist. Nonlinear aerodynamic modeling of unstable aircraft using flight test data. In *Proceedings of the 28th Congress of the International Council of the Aeronautical Sciences*, Brisbane, Australia, September 2012

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[OC3] R. Larsson and M. Enqvist. Real-time aerodynamic model parameter identification. In *Society of Flight Test Engineers International Symposium*, Linköping and Stockholm, Sweden, September 2009

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# Other scientific contributions

[O1] M. Enqvist. Variance-bias tradeoff in finite impulse response estimates obtained by correlation analysis. Technical Report LiTH-ISY-R-2416, Department of Electrical Engineering, Linköping University, Linköping, Sweden, 2002

# Patents

[P1] F. Gustafsson, P. Connman, O. Öberg, M. Enqvist, and N. Odelholm. A system and method for simulation of non-linear audio equipment. Patent no. SE525332, Pending patent no. EP1492081, US2004258250, JP2005020740, 2003